

$$L = B \int_{t=0}^{\infty} e^{-\beta t} \frac{c(t)^{1-\theta}}{1-\theta} dt + \lambda \left[K(n) + \int_{t=0}^{\infty} e^{-R(t)} w(t) e^{(n+g)t} dt - \int_{t=0}^{\infty} e^{-R(t)} c(t) e^{(n+g)t} dt \right]$$

$$B e^{-\beta t} \frac{1-\theta}{1-\theta} c(t)^{-\theta} - \lambda e^{-R(t)} e^{(n+g)t} = 0$$

$$L = u(x, y) + \lambda (I - P_x x - P_y y)$$

$$u'_x - \lambda P_x = 0 \Rightarrow u'_x = \lambda P_x \quad \frac{u'_x}{u'_y} = \frac{P_x}{P_y}$$

$$u'_y - \lambda P_y = 0 \Rightarrow u'_y = \lambda P_y$$

$$B e^{-\beta t} c(t)^{-\theta} = \lambda e^{-R(t) + (n+g)t} \int_{c=c}^t r(c) dc$$

$$\ln B - \beta t - \theta \ln c(t) = \ln \lambda - R(t) + (n+g)t$$

$$-\beta - \theta \frac{\dot{c}(t)}{c(t)} = -r(t) + (n+g)$$

$$\frac{\dot{c}(t)}{c(t)} = \frac{r(t) - n - g - \beta}{\theta}$$

$$\beta = f - (1-\theta)g - n$$

مقادیر اولی

$$\frac{\dot{c}(t)}{c(t)} = \frac{r(t) - \cancel{n} - \cancel{g} - f + (1-\theta)g + \beta}{\theta}$$

نرخ رشد بلندمدت

$$\frac{\dot{c}(t)}{c(t)} = \frac{r(t) - f - \theta g}{\theta} = \frac{r(t) - f}{\theta} - g$$

نرخ رشد بلندمدت

$$\frac{\dot{c}(t)}{c(t)} = \frac{\dot{A}(t)}{A(t)} + \frac{\dot{c}(t)}{c(t)} = \frac{r(t) - f}{\theta} = 0$$

$\bar{c} = c_t = c_{t+1}$ Steady State

$$r = f$$

$$B e^{-\beta t} c(t)^{-\theta} \Delta c$$

طلبت برای سنجش تغییرات
تغییرات در Δc

$$B e^{-\beta(t+\Delta t)} c(t+\Delta t)^{-\theta} \Delta c$$

دوره

$$c(t+\Delta t) = c(t) e^{\frac{\dot{c}(t)}{c(t)} \Delta t}$$

$$C(t+\Delta t) = C(t) e^{\frac{\dot{C}(t)}{C(t)} \Delta t}$$

$$B e^{-\beta(t+\Delta t)} C(t)^{-\theta} e^{\frac{\dot{C}(t)}{C(t)} \theta \Delta t} \Delta C e^{(r(t)-n-g)\Delta t}$$

$$B e^{-\beta t} C(t)^{-\theta} \Delta C = B e^{-\beta(t+\Delta t)} C(t)^{-\theta} e^{-\frac{\dot{C}(t)}{C(t)} \theta \Delta t} \Delta C e^{(r(t)-n-g)\Delta t}$$

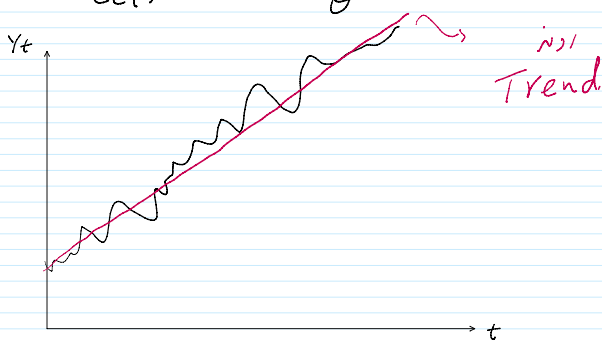
$$1 = e^{-\beta \Delta t} e^{-\frac{\dot{C}(t)}{C(t)} \theta \Delta t} e^{(r(t)-n-g)\Delta t}$$

logarithm al

$$0 = -\beta \Delta t - \frac{\dot{C}(t)}{C(t)} \theta \Delta t + (r(t)-n-g) \Delta t$$

$$\theta \frac{\dot{C}(t)}{C(t)} = r(t) - n - g - \beta$$

$$\frac{\dot{C}(t)}{C(t)} = \frac{r(t) - \beta - \theta g}{\theta}$$



State variable

مقدار مصرف

$$\dot{C} = 0$$

$$\frac{\dot{C}(t)}{C(t)} = \frac{f'(k(t)) - \beta - \theta g}{\theta} = 0$$

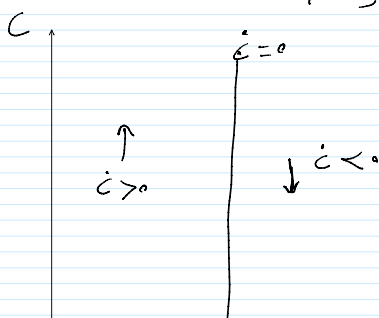
$$f'(k) = \beta + \theta g$$

$$f(k) = k^\alpha$$

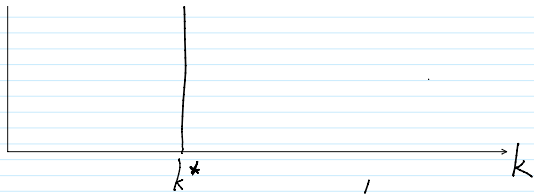
$$f'(k) = \alpha k^{\alpha-1} = \beta + \theta g$$

$$k^* = \left(\frac{\beta + \theta g}{\alpha} \right)^{\frac{1}{\alpha-1}}$$

$$k^* = \left(\frac{\alpha}{\beta + \theta g} \right)^{\frac{1}{1-\alpha}}$$



بودن C

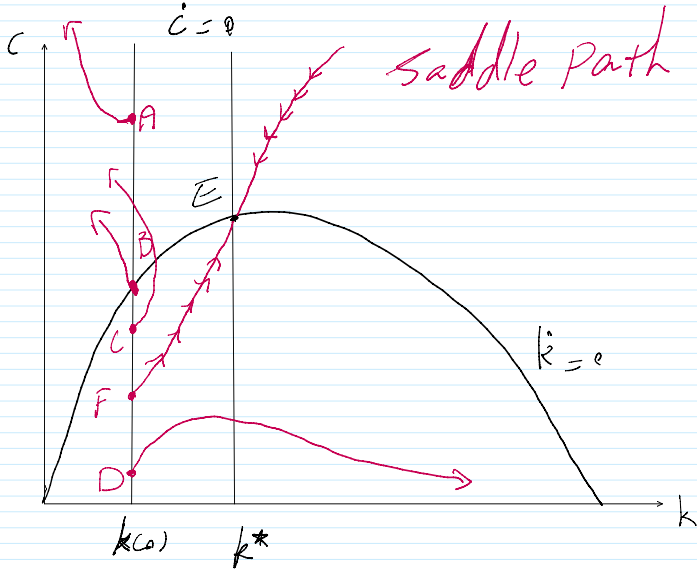
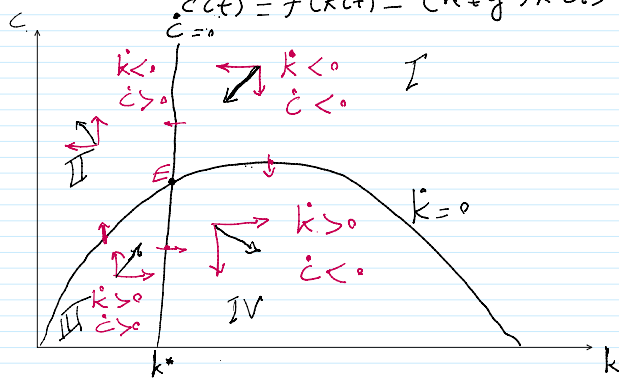


if $k < k^* \Rightarrow f'(k) > f'(k^*)$

$k < c_0$

$$\dot{k}(t) = f(k(t)) - c(t) - (n+g)k(t) = 0$$

$$\dot{c}(t) = f'(k(t)) - (n+g)c(t) = 0$$



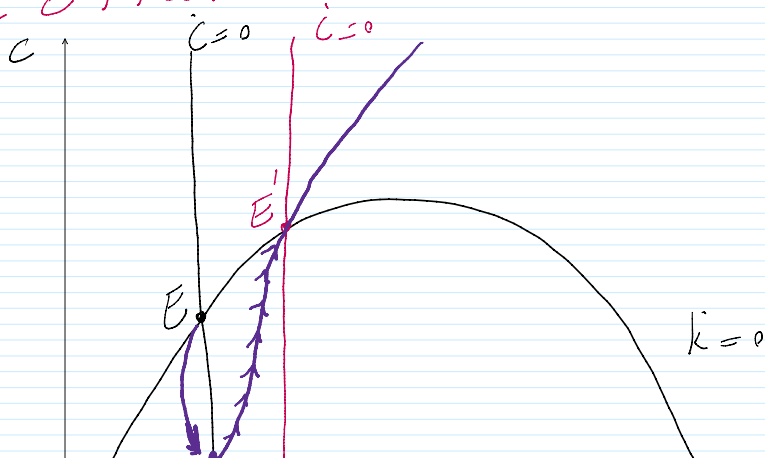
$$r = \rho$$

$$f'(k^*) = \rho$$

$$f(k_G^*) = n$$

$$k_G^* > k^*$$

The Effects of a Fall in the Discount Rate

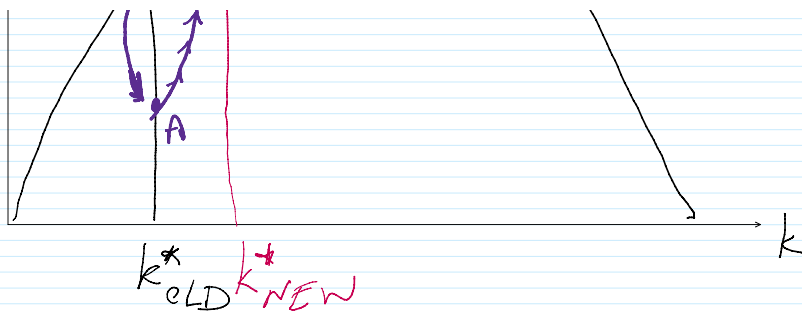


$$f'(k_{OLD}^*) = \rho_0$$

$$f'(k_{NEW}^*) = \rho_1$$

$$\rho_1 < \rho_0$$

$$k_{NEW}^* > k_{OLD}^*$$



$$k_{NEW}^* > k_{OLD}^*$$

The Rate of Adjustment and the slope of Saddle Path

$$\dot{c} \approx \frac{\partial \dot{c}}{\partial k} (k - k^*) + \frac{\partial \dot{c}}{\partial c} (c - c^*)$$

$$\dot{k} \approx \frac{\partial \dot{k}}{\partial k} (k - k^*) + \frac{\partial \dot{k}}{\partial c} (c - c^*)$$

$$\tilde{k} \equiv k - k^* \quad \tilde{c} \equiv c - c^*$$

$$\dot{\tilde{c}} = \dot{c} \quad \dot{\tilde{k}} = \dot{k}$$

$$\dot{\tilde{c}} \approx \frac{\partial \dot{c}}{\partial k} \tilde{k} + \frac{\partial \dot{c}}{\partial c} \tilde{c}$$

$$\dot{\tilde{k}} \approx \frac{\partial \dot{k}}{\partial k} \tilde{k} + \frac{\partial \dot{k}}{\partial c} \tilde{c} \quad \leftarrow$$

$$\frac{\dot{c}}{c} = \frac{f'(k^*) - \rho - \theta g}{\theta} \ll$$

$$\dot{c} = \left[\frac{f'(k^*) - \rho - \theta g}{\theta} \right] c$$

$$\frac{\partial \dot{c}}{\partial c} = \frac{\partial \dot{\tilde{c}}}{\partial c} \quad c^*, k^*$$

$$\frac{\partial \dot{c}}{\partial k} = \frac{\partial \dot{\tilde{c}}}{\partial k}$$

$$\cdot \quad f', k, \rho, \theta g \quad \leftarrow$$

$$\frac{\partial \dot{c}}{\partial c} = \frac{f'(k^*) - f - \theta g}{\theta} = 0 \quad \leftarrow$$

$$\frac{\partial \dot{c}}{\partial k} = \frac{f''(k^*) c^*}{\theta}$$

$$\dot{c} = \frac{f''(k^*) c^*}{\theta} \tilde{k}$$

$$\dot{k} = f(k) - c - (n+g)k$$

$$\frac{\partial \dot{k}}{\partial k} = f'(k^*) - (n+g)$$

$$\frac{\partial \dot{k}}{\partial c} = -1$$

$$\dot{k} \approx [f'(k^*) - (n+g)] \tilde{k} - \tilde{c}$$

$$f'(k^*) = f + \theta g$$

$$\dot{k} \approx [f + \theta g - (n+g)] \tilde{k} - \tilde{c}$$

$$\frac{\dot{k}}{k} \approx \beta \frac{\tilde{k}}{k} - \frac{\tilde{c}}{k}$$

$$\tilde{k} \approx \frac{f''(k^*) c^*}{\theta} \tilde{k}$$

$$\frac{\partial^2 \sigma}{\partial \alpha^2} \approx \frac{f''(k^*) c^*}{\theta} \approx \frac{\tilde{c}}{k}$$

$$\frac{\partial \sigma}{\partial \alpha} \approx \beta - \frac{\tilde{c}}{k}$$

$$\frac{\partial^2 \sigma}{\partial \alpha^2} \approx \frac{f''(k^*) c^*}{\theta} \approx \frac{\tilde{c}}{k}$$

$$\frac{\partial \sigma}{\partial \alpha} = c^*$$

$$\frac{\partial \sigma}{\partial \alpha} = \frac{c^*}{c - c^*}$$

$$\frac{\partial \sigma}{\partial \alpha} = \frac{\tilde{c}}{k}$$

$$\frac{c^*}{c} \neq \frac{c^*}{c - c^*}$$

$$\frac{\partial \sigma}{\partial \alpha} = \mu \approx \frac{f''(k^*) c^*}{\theta} \approx \frac{\tilde{c}}{k}$$

$$\frac{\tilde{c}}{k} = \frac{f''(k^*) c^*}{\theta} \cdot \frac{1}{\mu}$$

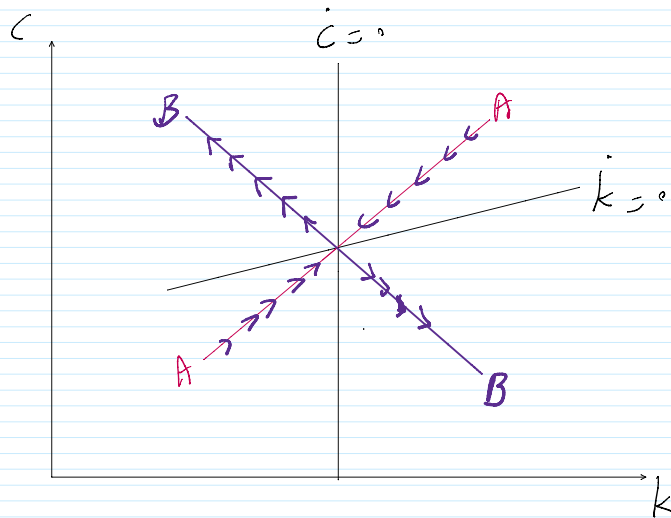
$$\mu = \beta - \frac{\tilde{c}}{k}$$

$$\mu = \beta - \frac{f''(k^*) c^*}{\theta} \frac{1}{\mu}$$



$$\mu^2 - \beta\mu + \frac{f'(k^*)c^*}{\theta} = 0$$

$$\mu = \frac{\beta \pm [\beta^2 - 4 \frac{f'(k^*)c^*}{\theta}]^{1/2}}{2}$$



The Effects of Government Purchase:

$$Y = C + I + G$$

$$\dot{k}(t) = f(k(t)) - c(t) - G(t) - (n+g)k(t)$$

$$\int_{t=0}^{\infty} e^{-R(t)} c(t) e^{(n+g)t} dt \leq k(0) + \int_{t=0}^{\infty} e^{-R(t)} [w(t) - G(t)] e^{(n+g)t} dt$$

$$G(t) = \underbrace{T(t)}_{w_0}$$

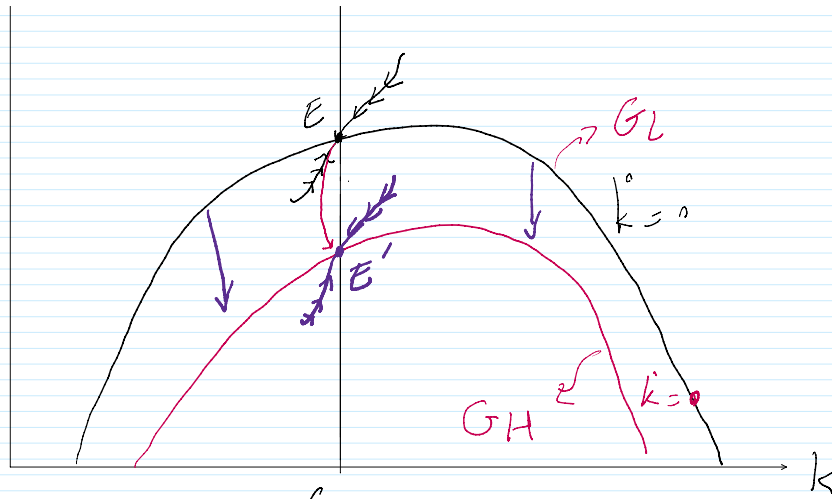
$$G_L \rightarrow G_H \quad G_H > G_L$$



افزایش دولت مخارج
دولت از G_L به G_H

l t

دولت از G_L به G_H



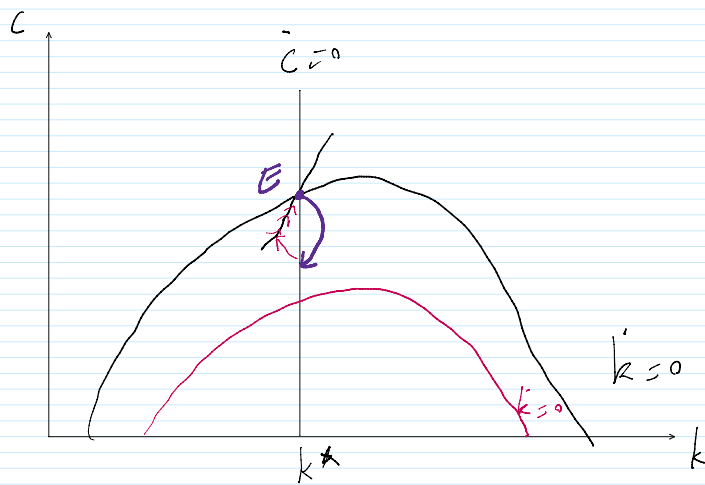
$$\dot{c} = 0 \quad f'(k^*) = f + \theta g$$

$$\dot{k} = 0 \quad f(k^*) - c^* - G^* - (n+g)k^* = 0$$

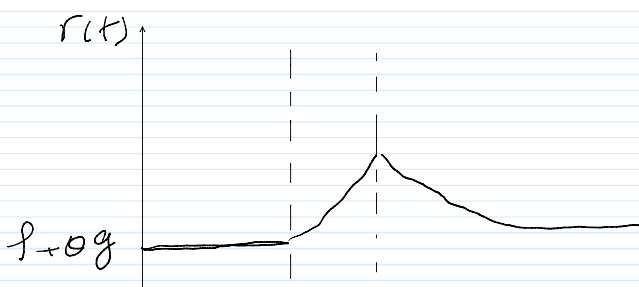
$$c^* = f(k^*) - G^* - (n+g)k^*$$

$$G_L^* \rightarrow G_H^* \uparrow$$

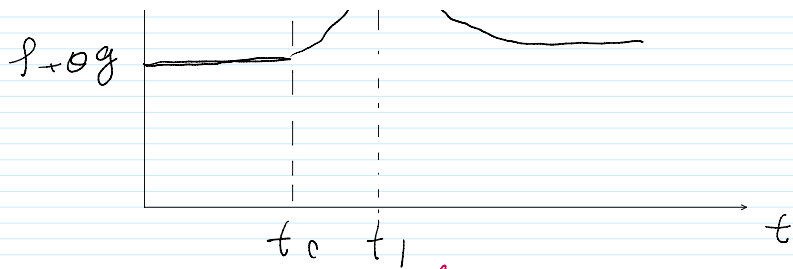
افزایش دولت از G_L به G_H



Consumption Smoothing



$$r(t) = f'(k(t))$$



The Diamond Model:

Overlapping-generations

نقد های جدید

$$c(t) \quad \bar{c}$$

$$c_t \quad \bar{c}$$

$$L_t = (1+n) L_{t-1}$$

$$c_{1t}, c_{2t}$$

$$U_t = \frac{c_{1t}^{1-\theta}}{1-\theta} + \frac{1}{1+\beta} \frac{c_{2t+1}^{1-\theta}}{1-\theta}$$

ALD

$$\theta > 0, \beta > -1$$

$$\frac{1}{1+\beta} > 1 \quad 1 + \beta < 1$$

$$\beta < 0$$

$$A_t = (1+g) A_{t-1}$$

$$Y_t = F(K_t, A_t L_t)$$

$$y_t = f(k_t)$$

$$r_t = f'(k_t)$$

$$w_t = f(k_t) - k_t f'(k_t)$$

$$K_{t+1} = w_t A_t L_t - c_{1t} L_t = (w_t A_t - c_{1t}) L_t$$

$$K_{t+1} = w_t A_t L_t - c_{1t} L_t = (w_t A_t - c_{1t}) L_t$$

$$S_t = \bar{I}_t = K_{t+1} - K_t + \delta K_t$$

$$I_t = K_{t+1} = (w_t A_t - c_{1t}) L_t$$

$$c_{1t}, c_{2t}$$

$$K_{t+1} = (1 - \delta) K_t + \bar{I}_t$$

Household Behavior:

$$c_{2t+1} = (1 + r_{t+1})(w_t A_t - c_{1t})$$

$$\frac{c_{2t+1}}{1 + r_{t+1}} = w_t A_t - c_{1t}$$

$$c_{1t} + \frac{c_{2t+1}}{1 + r_{t+1}} = w_t A_t$$

$$\text{Max } U_t = \frac{c_{1t}^{1-\theta}}{1-\theta} + \frac{1}{1+\beta} \frac{c_{2t+1}^{1-\theta}}{1-\theta}$$

s.t.

$$c_{1t} + \frac{c_{2t+1}}{1 + r_{t+1}} = w_t A_t$$

$$\mathcal{L} = \frac{c_{1t}^{1-\theta}}{1-\theta} + \frac{1}{1+\beta} \frac{c_{2t+1}^{1-\theta}}{1-\theta} + \lambda \left[A_t w_t - \left(c_{1t} + \frac{1}{1+r_{t+1}} c_{2t+1} \right) \right]$$

$$\frac{\partial \mathcal{L}}{\partial c_{1t}} = c_{1t}^{-\theta} - \lambda = 0 \Rightarrow \lambda = c_{1t}^{-\theta}$$

$$\partial C_{1t}$$

$$\frac{\partial L}{\partial C_{2t}} = \frac{1}{1+f} C_{2t+1}^{-\theta} - \frac{\lambda}{1+r_{t+1}} = 0$$

$$\frac{\partial L}{\partial \lambda} = A_t w_t - \left(C_{1t} + \frac{1}{1+r_{t+1}} C_{2t+1} \right) = 0$$

$$\frac{C_{1t}^{-\theta}}{1+r_{t+1}} = \frac{1}{1+f} C_{2t+1}^{-\theta}$$

$$C_{1t}^{-\theta} = (1+r_{t+1}) \left[\frac{1}{1+f} C_{2t+1}^{-\theta} \right]$$

$$C_{1t} = \left(\frac{1+f}{1+r_{t+1}} \right)^{\frac{1}{\theta}} C_{2t+1}$$

$$C_{2t+1} = \left(\frac{1+r_{t+1}}{1+f} \right)^{\frac{1}{\theta}} C_{1t}$$

$$C_{1t} + \frac{1}{1+r_{t+1}} C_{2t+1} = w_t A_t$$

$$C_{1t} + \frac{1}{1+r_{t+1}} \left(\frac{1+r_{t+1}}{1+f} \right)^{\frac{1}{\theta}} C_{1t} = w_t A_t$$

$$C_{1t} + \frac{(1+r_{t+1})^{\frac{1-\theta}{\theta}}}{(1+f)^{\frac{1}{\theta}}} C_{1t} = w_t A_t$$

$$\star \left[\frac{(1+f)^{\frac{1}{\theta}} + (1+r_{t+1})^{\frac{1-\theta}{\theta}}}{(1+f)^{\frac{1}{\theta}}} \right] C_{1t} = w_t A_t$$

$$\underbrace{L \frac{(1+\beta)^{\frac{1}{\theta}}}{\theta}}_Z$$

##

$$S_t = w_t A_t - C_t = w_t A_t - \frac{1}{2} w_t A_t = \frac{1}{2} w_t A_t$$

$$\Rightarrow C_t = \frac{1}{2} w_t A_t$$

$$s(r) = \frac{(1+r)^{\frac{1-\theta}{\theta}}}{(1+\beta)^{\frac{1}{\theta}} + (1+r)^{\frac{1-\theta}{\theta}}}$$

$$C_{t+1} = (1 - s(r_{t+1})) A_{t+1} w_t$$

$$\Lambda = (1+r)^{\frac{1-\theta}{\theta}}$$

$$s(r) = \frac{\Lambda}{(1+\beta)^{\frac{1}{\theta}} + \Lambda}$$

$$\frac{\partial s(r)}{\partial r}$$

$$\frac{\partial s(r)}{\partial r} = \frac{\partial s(r)}{\partial \Lambda} \cdot \frac{\partial \Lambda}{\partial r} =$$

$$\frac{\partial s(r)}{\partial \Lambda} = \frac{(1+\beta)^{\frac{1}{\theta}} - \Lambda}{((1+\beta)^{\frac{1}{\theta}} + \Lambda)^2}$$

$$\frac{\partial \Lambda}{\partial r} = \frac{1-\theta}{\theta} (1+r)^{\frac{1-2\theta}{\theta}}$$

$$\Lambda = (1+r)^{\frac{1-\theta}{\theta}}$$

$$\frac{\partial s(r)}{\partial r} = \frac{(1+\beta)^{\frac{1}{\theta}}}{[(1+\beta)^{\frac{1}{\theta}} + \Lambda]^2} \cdot \frac{1-\theta}{\theta} (1+r)^{\frac{1-\theta}{\theta}}$$

$\int_t A_t$

نسخه

$\frac{20}{0}$

$$\begin{aligned} & \text{if } \theta < 1 \quad \frac{\partial s(r)}{\partial r} < 0 \\ & \text{if } \theta > 1 \quad \frac{\partial s(r)}{\partial r} > 0 \\ & \text{if } \theta = 1 \quad \frac{\partial s(r)}{\partial r} = 0 \end{aligned}$$

The Dynamics of Model:

$$K_{t+1} = w_t A_t L_t - C_{t+1} L_t = (w_t A_t - C_{t+1}) L_t$$

$$K_{t+1} = s(r_{t+1}) \cdot A_t w_t L_t$$

$$k_{t+1} = \frac{K_{t+1}}{A_{t+1} L_{t+1}} = \frac{s(r_{t+1}) A_t w_t L_t}{A_{t+1} L_{t+1}} = \frac{s(r_{t+1}) w_t}{\frac{A_{t+1}}{A_t} \frac{L_{t+1}}{L_t}}$$

$$k_{t+1} = \frac{s(r_{t+1}) w_t}{(1+g)(1+n)} = \frac{1}{(1+g)(1+n)} s(f'(k_{t+1})) [f(k_t) - k_t]$$

$$k_{t+1} = k_t = k$$

$$y = f(k_t) = k_t^\alpha \Rightarrow f'(k_t) = \alpha k_t^{\alpha-1}$$

$$\theta = 1$$

$$s(r) = \frac{(1+r)^{\frac{1-\theta}{\theta}}}{(1+f)^{\frac{1}{\theta}} + (1+r)^{\frac{1-\theta}{\theta}}} = \frac{1}{1+f+1} = \frac{1}{2}$$

$$f'(k_t)$$



$$+ f$$

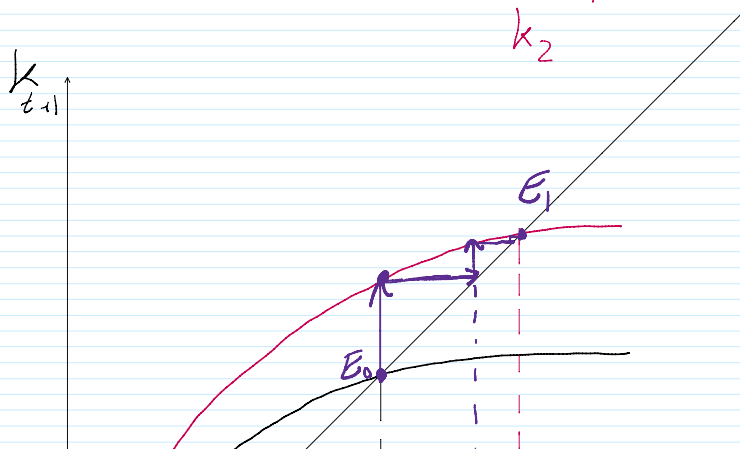
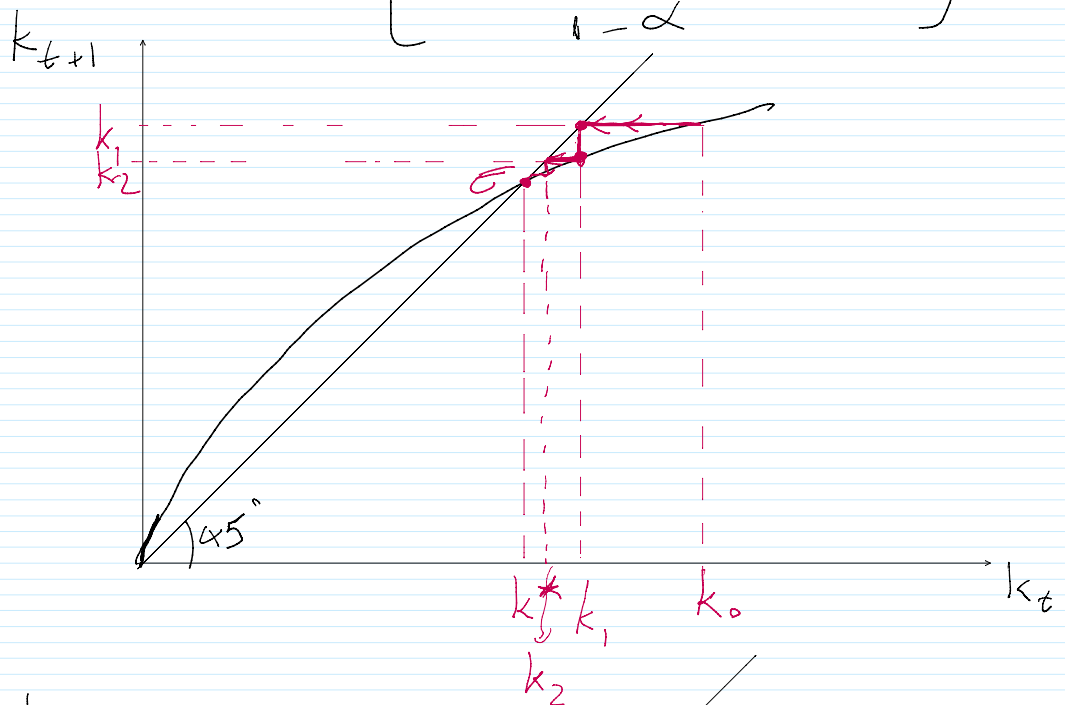
$$s(c) = \frac{1}{(1+f)^{\frac{1}{\theta}} + (1+r)^{\frac{1-\theta}{\theta}}} = \frac{1}{1+f+1} \quad 2$$

$$k_{t+1} = \frac{1}{(1+g)(1+n)} \frac{1}{2+f} \left[k_t^\alpha - k_t \alpha k_t^{\alpha-1} \right]$$

$$k_{t+1} = \frac{(1-\alpha)}{(1+g)(1+n)(2+f)} k_t^\alpha$$

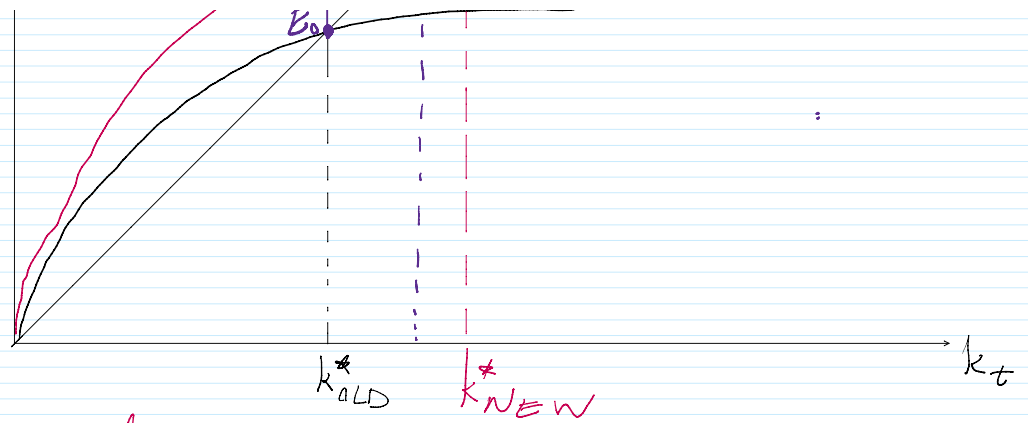
$$k^* = k_{t+1} = k_t \Rightarrow k^{1-\alpha} = \frac{(1+g)(1+n)(2+f)}{1-\alpha}$$

$$k^* = \left[\frac{(1+g)(1+n)(2+f)}{1-\alpha} \right]^{\frac{1}{1-\alpha}}$$



+ f

}



The speed of convergence:

$$k_{t+1} = \frac{(1-\alpha)}{(1+n)(1+g)(2+\beta)} k_t^\alpha$$

$$k^* = \frac{(1-\alpha)}{(1+n)(1+g)(2+\beta)} k^{*\alpha}$$

$$k^* = \left[\frac{1-\alpha}{(1+n)(1+g)(2+\beta)} \right]^{\frac{1}{1-\alpha}}$$

$$j^* = \left[\frac{1-\alpha}{(1+n)(1+g)(2+\beta)} \right]^{\frac{\alpha}{1-\alpha}}$$

$$k_{t+1} \approx k^* + \left(\frac{dk_{t+1}}{dk_t} \Big|_{k=k^*} \right) (k_t - k^*)$$

$$k_{t+1} - k^* \approx \lambda (k_t - k^*)$$

که سرعت همگامی

$$k_{t+1} - k^* \approx \lambda^t (k_0 - k^*)$$

$$\lambda = \frac{dk_{t+1}}{dk_t} \Big|_{k_t=k^*} = \frac{\alpha(1-\alpha)}{(1+n)(1+g)(2+\beta)} k^{*\alpha-1}$$

$$\lambda = \alpha \frac{(1-\alpha)}{(1+n)(1+g)(2+\beta)} \left[\frac{1-\alpha}{(1+n)(1+g)(2+\beta)} \right]^{\frac{\alpha}{1-\alpha}}$$

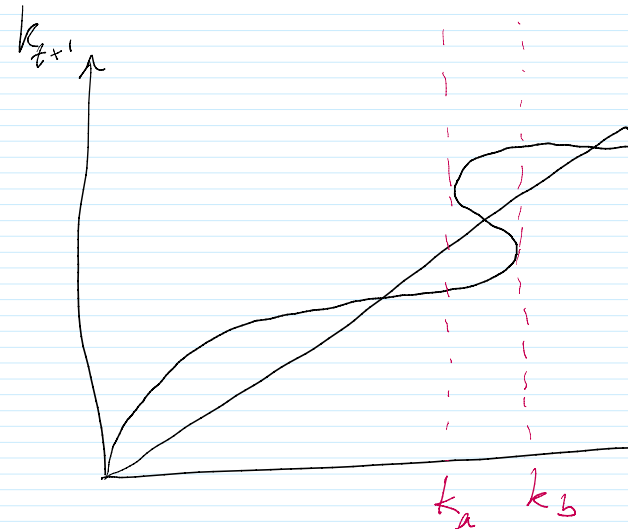
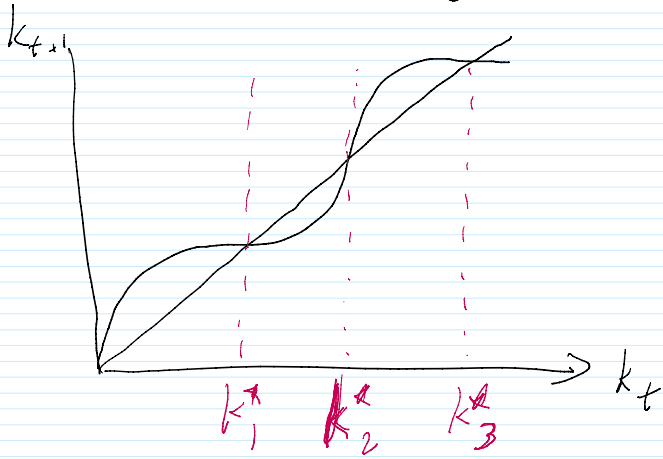
$$\lambda = \alpha$$

$$\frac{\alpha - 1}{1 - \alpha}$$

The General Case:

$$k_{t+1} = \frac{1}{(1+n)(1+g)} s(f'(k_{t+1}))$$

$$\frac{f(k_t) - k_t f'(k_t)}{f(k_t)}$$



Government in the Diamond Model:

$$G_t = T_t$$

$$(1-\alpha)k_t^\alpha - G_t$$

$$k_{t+1} = \frac{1}{(1+n)(1+g)(2+\beta)} [(1-\alpha)k_t^\alpha - G_t]$$



)

$\rightarrow k_t$

$\rightarrow k_t$

